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Reaching nirvana with a defaultable asset?

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Notes

- 1. Cox and Huang (1989) require the global Lipschitz continuity of the diffusive coefficient for the risky asset-value process [see Conditions A and B at p. 46 in Cox and Huang (1989)]. By contrast, the diffusive coefficient in our setting is the square root of the risky asset value.
- 2. See, for instance, Davydov and Linetsky (2001), p. 952, first paragraph, with \ $(S \{t\}=P \{t\}\) and \(p=\frac{1}{2}.\)$

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- 7. Similar investment-horizon effects have been found in the literature on dynamic portfolio choice with a risky non-defaultable asset characterized by a mean-reverting drift and a constant volatility [see, for example, Koijen et al. (2009)].
- 8. The functions U and V are conjugate if and only if $\langle U(w) = \inf_{y>0} (V(y) + wy) \rangle$ and $\langle V(y) = \sup_{w>0} (U(w) wy) \rangle$.

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We apply to problem (<u>A.1</u>) the duality approach developed by Kramkov and Schachermayer (<u>1999</u>, <u>2003</u>). To this aim, we observe that the utility function U satisfies Inada conditions [equation (2.4) in Kramkov and Schachermayer (<u>1999</u>)]. Let V denote the conjugate function of U, that is $V(y) = \frac{1-\pi v}{1-\pi v}$ and define

```
$$\begin{aligned} v(y)=E\left[ V\left( y\eta \right) \right] \end{aligned}$$
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1.2 A.2 Proof of proposition 3.2

Since $(a=\frac{1-\phi}{\theta})$, then

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\label{left} $$\left( \left( \frac{1-\pi} \right) \right) = 1-\pi \left( \frac{1-\pi} \right) \left(
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 $$\ M_{T}=\exp \left( \frac{a^{2}+a}{2}\right) \\ = \left( \frac{a^
```

that allows us to find (A.4). By imposing 0 drift on the Ito decomposition under \ ($\{\hat{Q}\}\$) of the process \(M_{t}\) we get the partial differential equation for G

 $\$ \left{ \begin{array} [c]{l} G_{t}=\frac{\pi^{2}}

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\(M_{t}\) is a martingale we define
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\qquad \qquad \ \text{t}=\frac{M_{t}}{M_{0}}, \end{aligned}
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which is a $({\hat Q})\)$ local martingale as well, and show that $(\hat z_{t})$ is a $({\hat Q})\)$ martingale. To this aim, we first observe that process $(\hat z_{t})$ is a stochastic exponential. In fact, Ito formula implies that

```
 $\$\left(a^{2}+a\right)^{t}=e^{\frac{a^{2}+a}{2}} int $$ _{0}^{t}Y_{s}ds}\frac{\theta}{\theta} $$ Y_{t}^{t}\d\theta $$
```

from the dynamics of Y with respect to $({\hat Q})$ in Eq. (A.5). Since $(\frac{\nabla Y}{t}g(T-t)) = (T-t)$

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We apply Theorem 4.1 in Klebaner and Lipster (2014) to conclude that \(\mathfrak $\{z\}_{\{t\}}$ \) is a true martingale. In particular, with Klebaner and Lipster notations (4.2) at page 44

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\label{thm:left:chi} $\ \g(t)=2\ \g(t)=2\ \g(t)\ \g(t)=2\ \g(t)\ \g(t)
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 $$\left(y\right)_{s}(y) + \left(b_{s}(y)\right)^{2} + 4c \phi y \ \ \ L_{s}(y) = 2y \left(b_{s}(y)\right)^{2} + 4c \phi y \ \ L_{s}(y) = 2y \left(a_{s}(y) + b_{s}(y)\right)^{2} \right)^{2} + 8c \phi y^{2} + 8c \phi y^{2} + 8c \phi y^{2} + 8c \phi y^{2} \right) $$
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denote with $(Z_{t}^{\mathbf{t}}^{\mathbf{t}})$ the (\mathbb{Q}) -Brownian motion

Before proving the result, we first list some technical lemmas.

Lemma A.1

(A.10)

Let $(L^{*}=\frac{L_{T}}{\hat Q})$ where (L_{T}) is given by (A.2). Then $(L_{t}^{*}=E^{\mathbf Q})$ left[$L^{*}|\mathcal G F_{t}\cap G$] values the stochastic differential equation

##\bagin (aligned) dI_(+) ^ (*) _(a + 1)I_(+) ^ (*)\agn+ (V_(+)) d7_(+) ^ (\max + bbb)

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and from the definitions of (α) in (2.3) and of L in (A.2) that

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 $$\left( L_{T}\right) = \exp \left( a \right) - {T} \operatorname{Y_{s}} dZ_{s}-\frac{L_{T}}{\cot _{0}^{T}} \operatorname{Y_{s}} dZ_{s}-\frac{a^{2}}{2} \int_{0}^{T}Y_{s} ds+ \int_{0}^{T}\operatorname{Y_{s}} dZ_{s}+\frac{1}{2} \int_{0}^{T}Y_{s} ds+ \int_{0}^{T}Y_{s}
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From the definition of $(Z \{s\}^{\mathbb{Q}})$ in Eq. (A.10) we get

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$$\left( \left( \frac{T}^{*}&=\left( \left( \frac{1-1\right) \right) \right) -\left( \frac{T}^{*}&=\left( \frac{T}^{*}&=\left( \frac{1-1}\right) \right) -\left( \frac{T}^{*}&=\left( \frac{T}^{*}&=\left( \frac{T}^{*}\right) \right) -\left( \frac{T}^{*}&=\left( \frac{T}^{*}&=\left( \frac{T}^{*}&=\left( \frac{T}^{*}\right) \right) -\left( \frac{T}^{*}&=\left( \frac{T}^{*}&=\left( \frac{T}^{*}&=\left( \frac{T}^{*}\right) \right) -\left( \frac{T}^{*}&=\left( \frac
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```
\label{eq:maigned} $M_{t}=e^{\frac{a^{2}+a}{2}\in _{0}^{t}Y_{s}ds}e^{Y_{t}g(T-t)}. \end{aligned} $$
```

Then we have

where $\(\Delta_3 \)$ and $\(Z_{t}^{\) \} \)$ in Eq. (A.10).

Proof of the Lemma

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since \(d\{\{tilde\{P\}\}_{t}\}=\{\{t\}\}, t\}\}  and \(E^{Y}_{t}\}  \(E^{Y}_{t}\}, t\}  and \(E^{Y}_{t}\}  and
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```
because \(G(T,y)=\left(F(T,y)\right)^{\frac{1}{\phi}}=\{E\left(\frac{1-\phi}{\phi}\right)^{\frac{1}{\phi}}.\ It follows that the differential of the \(\Phi_{W})^{\frac{1}{\phi}} is given by
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 $$\left\{G(T,y)\right\}d\left(t\right)^{*}_{t}^{*}&=\left\{W\right\}G(T,y)\right\}d\left(t\right)^{*}M_{t}\right) \end{aligned} d_{t}^{*}_{t}^{*}&=\left\{W\right}G(T,y)\right]L_{t}^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(t\right)^{*}M_{t}\left(
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Comparing this equation with Eq. (A.13), we obtain

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\label{lighted} $$\left[ \left( xi \right)_{t}^{*} \right] = W^{*}(t)\left[ \left( 1 \right)_{t}^{*} \right] $$
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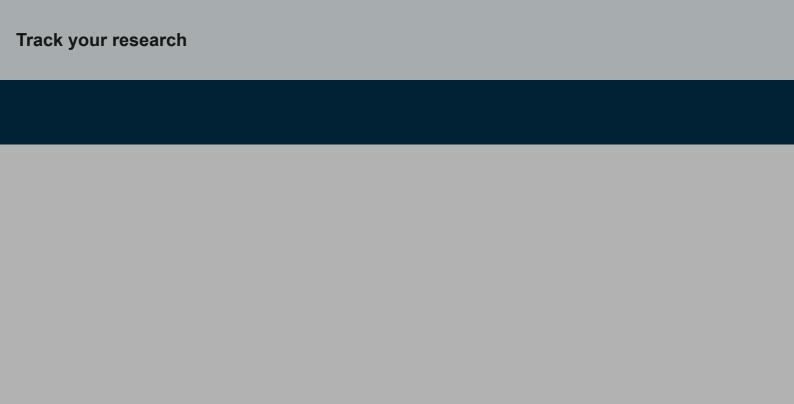
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