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Reaching nirvana with a defaultable asset?

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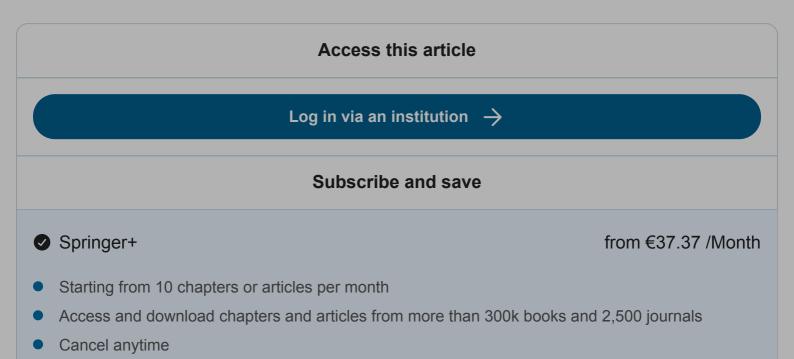
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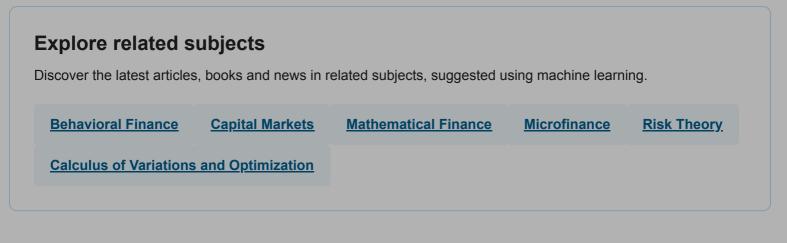
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Notes

 Cox and Huang (<u>1989</u>) require the global Lipschitz continuity of the diffusive coefficient for the risky asset-value process [see Conditions A and B at p. 46 in Cox and Huang (<u>1989</u>)]. By contrast, the diffusive coefficient in our setting is

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- 6. There are parameter values that make the investor with \(\phi >1\) take a net short position in the risky defaultable asset.
- Similar investment-horizon effects have been found in the literature on dynamic portfolio choice with a risky non-defaultable asset characterized by a mean-reverting drift and a constant volatility [see, for example, Koijen et al. (2009)].
- 8. The functions U and V are conjugate if and only if $(U(w)=\inf_{y>0} (V(y)+wy))$ and $(V(y)=\sup_{w>0} (U(w)-wy))$.

9. The superscript $(\left| \frac{\sqrt{1 + 1}}{2} \right)^{1}$ refers to the notations of Delbaen

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1.1 A.1 Proof of proposition <u>3.1</u>

The problem of utility maximization can be written as $(J(w)=\left(e^{T}\right))$ ^{1-\phi}u(w)\) where *u* is defined as

(A.1)

We apply to problem (A.1) the duality approach developed by Kramkov and Schachermayer (1999, 2003). To this aim, we observe that the utility function Usatisfies Inada conditions [equation (2.4) in Kramkov and Schachermayer (1999)]. Let V denote the conjugate function⁸ of U, that is $(V(y)=\frac{\phi}{1-\phi})^{1-\phi} y^{-\phi}(-\frac{1-\phi}{1-\phi})$ and define

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The value function is then

```
\label{eq:start} $$\begin{aligned} J(w)&=\left( e^{rT}\right) ^{1-\phi}E\left[ U({\tilde{W}}^{*})\right] = U(we^{rT})E\left[ \left( \rac{\eta ^{-\frac{1}}\phi}) + B(e^{rT})E\left[ \eta ^{-\frac{1}}\phi}) + B(e^{rT})E\left[ \eta ^{-\frac{1-\phi}}\phi} + C(we^{rT})), \left( E\left[ \eta ^{-\frac{1-\phi}}\phi}) + C(we^{rT})), \left( E\left[ \exp \eft( \rac{1-\phi}}\phi}) + C(we^{rT}))) + C(we^{rT})\phi \eft( E\left[ \exp \eft( \rac{1-\phi}\phi}\phi)) + C(phi) + C(phi) \eft( \e
```

\(\square \)

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The random variable (L_{T}) in (A.2) is the Radon-Nikodym density of a probability measure equivalent to $(\{ \mathbb{P} \})$. In fact, Theorem⁹ 2.3 in Delbaen and Shirakawa (2002) applied to $(S^{DS}=Y,) ((\rho^{DS}=0.5,)) ((\rho^{DS}=b>0), sigma ^{DS}=2(\rho^{T}(\rho^{DS})) ((\rho^{DS}=b+2a), \rho^{T}(\rho^{DS}))), and <math>(\rho^{TS}=a)$ implies that $(\rho^{T}^{DS}=L_{T})$ is the Radon-Nikodym density of an equivalent probability measure $(\{ \mathbb{P} \})$ equivalent to $(\{ \mathbb{P} \})$. Girsanov's theorem implies then that

```
\boldsymbol{Z}_{t}=Z_{t}-\int \{0^{t}a\
```

(A.3)

is a $({ \mathbf{Q}})$. Brownian motion. Thus,

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(A.6)

where G(t, y) is a \(\mathcal {C}^{1,2}\) function to be determined in such a way that (G(0,y)=1) and M is a $({\lambda_{0}})$ martingale. In particular, Eq. (A.6) implies for (t=0) that $(M_{0}=G(T,y))$ and for (t=T)

since (G(0, cdot)=1.) The martingality condition $(M_{0}=E^{{\rm L}}(M_{T}))$ yields then

 $\hat{Q}} \$

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Since (M_{t}) has 0 drift in the Ito decomposition under $({\lambda_{\lambda_{M}}})$, (M_{t}) is a $({\lambda_{M}})$ local martingale. To conclude that (M_{t}) is a martingale we define

 $\boldsymbol{z}_{t}= M_{0}\$, und aligned $\mathbf{z}_{t} = M_{0}\$

which is a $({\frac{\lambda_{1}}{0}}) local martingale as well, and show that (<math>(\max {z}_{t})) is a ({\lambda_{1}}) is a ({\lambda_{1}}) is a {Q}}) martingale. To this aim, we first observe that process ((<math>\max {z}_{t})) is a stochastic exponential$. In fact, Ito formula implies that

$\ \d M_{t}=e^{\frac{a^{2}+a}{2}}$

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with

```
\label{eq:spin} $$\begin{aligned} m_{t}=\int_{0}^{t}2\g(T-s)\g(T-s)\g(T-s)\d(t)_{s}\d(t)_{s}.\end{aligned} $$
```

We apply Theorem 4.1 in Klebaner and Lipster (2014) to conclude that (\mathbf{z}_{t}) is a true martingale. In particular, with Klebaner and Lipster notations (4.2) at page 44

 $\ \del{a_s}(y)=2\$

we get

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1.3 A.3 Proof of proposition 3.3

In what follows, we will mainly work under the martingale measure $(\mbox{Q},\)$ whose density with respect to $({\mbox{P}})$ is $(\ensuremath{\} (2.3)$. We denote with $(Z_{t}^{t}^{(\mbox{mathbb } {Q}))$ the $(\mbox{mathbb } {Q})$ -Brownian motion

 $\boldsymbol{Q}=Z_{t}+ int_{0}^{t}\$ \end{aligned}

(A.10)

Before proving the result, we first list some technical lemmas.

Lemma A.1

Let $(L^{*}=\frac{L_{T}}{\delta})$ where (L_{T}) is given by (<u>A.2</u>). Then δ

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 $\label{eq:p}} d{ \mathbb{P}} } d{ \mathbb{P}} } {d{\mathbb{P}}} } d{\mathbb{Q}} d{\mathbb{Q}} \\ end{aligned}$

and from the definitions of $(\langle L \rangle)$ in (2.3) and of L in (A.2) that

 $\label{eq:ligned} L_{T}^{*}&=\frac{L_{T}}{\eta}=\vec{L_{T}}{\eta}=\vec{L_{T}}_{\eta}=\v$

From the definition of $(Z_{s}^{)} \in \{Q\}\)$ in Eq. (A.10) we get

 $\scriptstyle digned L_{T}^{*} &= \left(\left(1 + 1 \right) \right) \right)$

 ${0}^{T}$

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Let (M_{t}) be the $({ \lambda_{0}}, namely$

Then we have

```
\label{eq:ligned} dM_{t}&=2\qt{c\phi Y_{t}}M_{t}g(T-t)d\at{Z}_{t}\&=2\qt{c\phi Y_{t}}M_{t}g(T-t)\dt{Z}_{t}\Add Q}-\frac{1}{\phi }\g(T-t)\dt{Y_{t}}dt\right) \nonumber \end{aligned}
```

(A.12)

where $((hat{Z}_{t}))$ is defined in (<u>A.3</u>) and $(Z_{t}^{ (mathbb {Q})})$ in Eq.

(<u>A.10</u>).

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```
_{t}^{*}}{\sqrt{Y_{t}}}dZ_{t}^{\mathbb {Q}} \end{aligned} $$ (A.13)
```

```
since (d{\tilde{P}}_{t}={\tilde{P}}_{t}sqrt{Y_{t}}sigma_{t}dt+ {\tilde{P}}_{t}sigma_{t}dZ_{t}={\tilde{P}}_{t}rac{xi } {\operatorname{V}_{t}}dZ_{t}^{mathbb} {Q}}) from (2.1) and (A.10).
```

```
Therefore, we look for the Ito representation of (\{ W\} ^{*} (t)=E^{\mathbf{W}}^{*} (t)=E^{\mathbf{W}}
```

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\label{eq:started} d\{\tilde\{W\}\_{t}^{*}\&=\frac\{w\}\{G(T,y)\}d\eft(L_{t}^{*}M_{t}\right) \&=\frac\{w\}\{G(T,y)\}L_{t}^{*}M_{t}\eft[\frac{1}{\phi}\+2\sqrt{c\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\mathbb}{Q}\quad \box \by\left( { A}.11\right) \text { and }\left( { A}.12\right) \&= \\{\tilde\{W\}\_{t}^{*}\eft[\frac{1}{\phi}\+2\sqrt{c\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}g(T-t)\right] \left[\frac{1}{\phi}\+2\sqrt{c\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}g(T-t)\right] \left[\frac{1}{\phi}\+2\sqrt{c\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}g(T-t)\right] \left[\frac{1}{\phi}\+2\sqrt{c\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}\eft[\frac{1}{\phi}\+2\sqrt{c\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}\eft[\frac{1}{\phi}\+2\sqrt{c\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}\eft[\frac{1}{\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}\eft[\frac{1}{\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}\eft[\frac{1}{\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}\eft[\frac{1}{\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}\eft[\frac{1}{\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}\eft[\frac{1}{\phi}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}g(T-t)\right] \sqrt{Y_{t}}g(T-t)\right] \sqrt{Y_{t}}dZ_{t}^{\phi}g(T-t)\right] \sqrt{Y_{t}}g(T-t)\right] \sqrt{Y_{t}}g(T-t)\right] \sqrt{Y_{t}}g(T-t)\right] \sqrt{Y_{t}}g(T-t)\right] \sqrt{Y_{t}}g(T-t)\right] \sqrt{Y_{t}}g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\right]g(T-t)\righ
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Comparing this equation with Eq. (A.13), we obtain

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